

The Power of Bayes: An Old Idea Revisited

C. Shane Reese, Department of Statistics, BYU

Outline

- Historical Perspective
- Overview of Statistical Framework
- Example: Computer Model Incorporation
- Example: Supercomputer Reliability
- Concluding Ideas for Computer Science

Historical Tour

- Bayes (1702-1761) was a Nonconformist minister with an interest in mathematics
- Papers:
 - Divine Providence and Government Is the Happiness of His Creatures* (1731)
 - An Introduction to the Doctrine of Fluxions, and a Defense of the Analyst* (1736)
 - Essay Towards Solving a Problem in the Doctrine of Chances* (1764)
- Richard Price, Laplace (1781).
- 1950's Bayes: Savage, deFinetti, Lindley.
- 1990's Bayes: Gelfand, Berger, Smith, Berry.

Definitions

- **Problem:** Unknown population parameter (θ) must be estimated.
 1. **Simple Example:**

θ = Probability that a selected person from the group can hit a target on the board with a ball from the back of the room.
 2. **Real Example 1:**

θ = Optimal steady-state thermodynamic operating point of a fluidized bed coating process for food coating.
 3. **Real Example 2:**

θ = Probability that a supercomputer constructed of 48 nodes in “parallel” can complete a 6 hour computer run with no failures.

Definitions

- Step 1 of either formulation is to pose a statistical (or probability) model for the random variable which represents the phenomenon.
 1. **Simple Example:**
a reasonable choice for $f(y|\theta)$ (the sampling density or likelihood function) would be that the number of successful hits (Y) on the target would follow a *binomial* distribution with the n throws and the probability of any one throw being a “hit” called θ
 2. **Real Example 1:**
Topic of next part of the talk.
 3. **Real Example 2:**
Topic later in the talk.

Definitions (cont)

- Classical Data Analysis
 1. all pertinent information enters the problem through the likelihood function in the form of data (Y_1, \dots, Y_n)

$$f(y_1, \dots, y_n | \theta) = \prod_{i=1}^n f(y_i | \theta)$$

2. objective in nature
3. software packages all have this capability
4. maximum likelihood, unbiased estimation, etc.
5. confidence intervals, difficult interpretation

Definitions (cont)

- Bayesian Data Analysis

1. data (enters through the likelihood function *as well as* allowance of other information

$$p(\theta|y_1, \dots, y_n) = \text{constant} \times \prod_{i=1}^n f(y_i|\theta) \times \pi(\theta).$$

2. reads: the *posterior distribution* [$p(\theta|y_1, \dots, y_n)$] is a constant multiplied by the likelihood [$\prod_{i=1}^n f(y_i|\theta)$] multiplied by the *prior distribution* [$\pi(\theta)$]
3. prior distribution: before any data collection, the view of the parameter
4. posterior distribution: in light of the data our updated view of the parameter

Prior Distributions

1. can come from expert opinion, historical studies, previous research, or general knowledge of a situation
2. there exists a “flat prior” or “noninformative” which represents a state of ignorance.
3. Attempting to capture physical theories, expert opinion, etc. in a probability distribution is often difficult.
4. See [Real Example 1](#) for an interesting example.

Definitions (cont)

- Bayesian Data Analysis (cont)
 1. inherently subjective (prior is controversial)
 2. few software packages have this capability
 3. result is a probability distribution
 4. *credible intervals* use the language that everyone uses anyway.
(Probability that θ is in the interval is .95.)
 5. see examples for demonstration.

Comparison

Bayesian	Classical
subjective	objective
little software	abundant software
direct interpretation	difficult interpretation
decision theory	hypothesis testing

Real Example 1

- Computer Experiments
- Difference From Field Trials (Experimental Data)
- Examples:
 1. Modern Industrial R&D
 2. Climate Modelling
 3. Biological/Nuclear Weapons Systems
 4. Modern Finance

Real Example 1

- Food coating example
- Observed Data: \mathbf{X} = temperature of fluid, velocity of fluid, etc. Y = thermodynamic operating point
- Computer model: Computational Fluid Dynamics Model combined with other physics theories to “predict” temperature
- Initial Design: Random LHS Design.

Data Structure

- Field observations:

$$y_f = (y_{f_1}, \dots, y_{f_n})'$$

where

$$y_{f_i} = \eta(x_i, \theta) + \delta(x_i) + \varepsilon_i, \quad i = 1, \dots, n.$$

- Computer code output:

$$y_c = (y_{c_1}, \dots, y_{c_m})'$$

where

$$y_{c_j} = \eta(x_j^*, t_j), \quad j = 1, \dots, m.$$

- Full set of data:

$$d^T = (y_c^T, y_f^T) = (y_{c_1}, \dots, y_{c_m}, y_{f_1}, \dots, y_{f_n}).$$

Likelihood & Priors

1. Model:

$\eta(\cdot, \cdot) \sim N(\mu_\eta, c_1\{(\cdot, \cdot), (\cdot, \cdot)\})$ with

$$c_1((x^*, t), (x^{*'}, t')) = \sigma_\eta^2 \cdot \exp\left\{-\sum_{k=1}^p \beta_k^\eta (x_k^* - x_k^{*'})^2 - \sum_{k'=1}^q \beta_{p+k'}^\eta (t_k - t_k')^2\right\}$$

$\delta(\cdot) \sim N(\mu_\delta, c_2(\cdot, \cdot))$ with

$$c_2(x, x') = \sigma_\delta^2 \cdot \exp\left\{-\sum_{k=1}^p \beta_k^\delta (x_k - x_k')^2\right\}$$

$$\varepsilon_i \sim N(0, \sigma_\varepsilon^2).$$

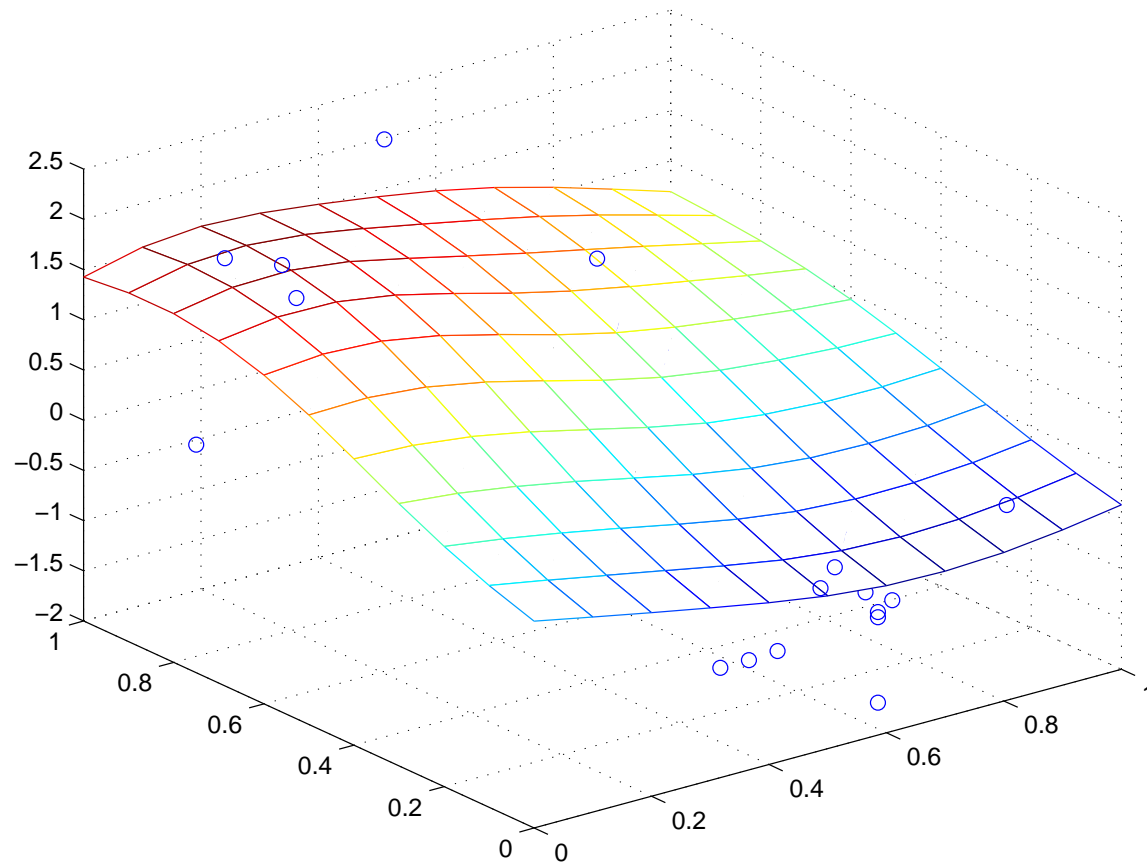
2. Parameters:

(a) $\Omega = \{\mu, \theta, \phi, \sigma_\varepsilon^2\}$

(b) $\mu = (\mu_\eta, \mu_\delta)^T$

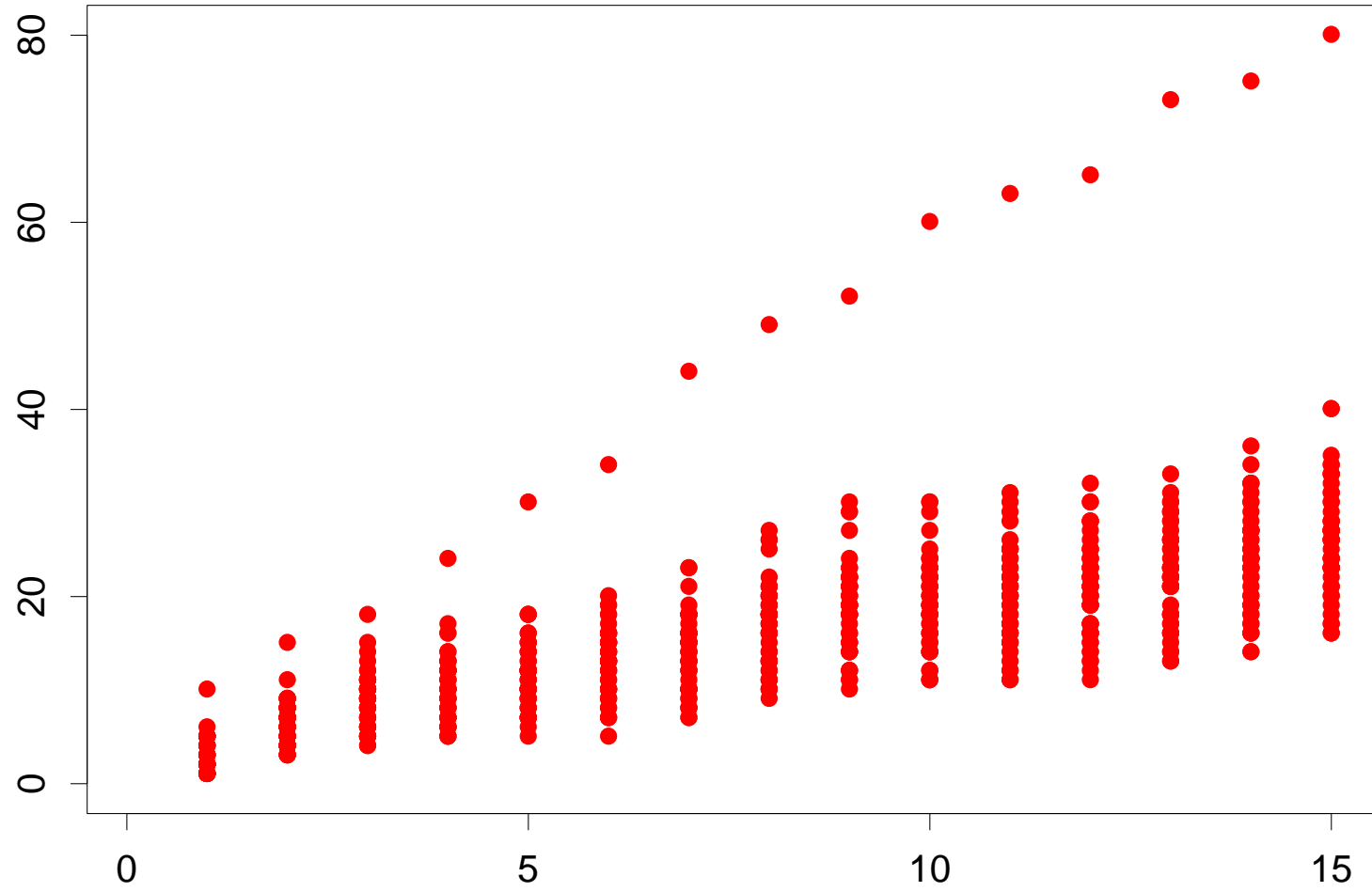
(c) $\phi = \{\sigma_\eta^2, \sigma_\delta^2, \beta^\eta, \beta^\delta\}$

“Prior” Surface with Data



Real Example 2

- Los Alamos National Laboratory Supercomputer: Blue Mountain
- Weapons development and maintenance: Stockpile Stewardship
- Problems in late 1999
- Goal: Calculate the probability of running a 6 hour job with no interruptions on a variety of architectures.



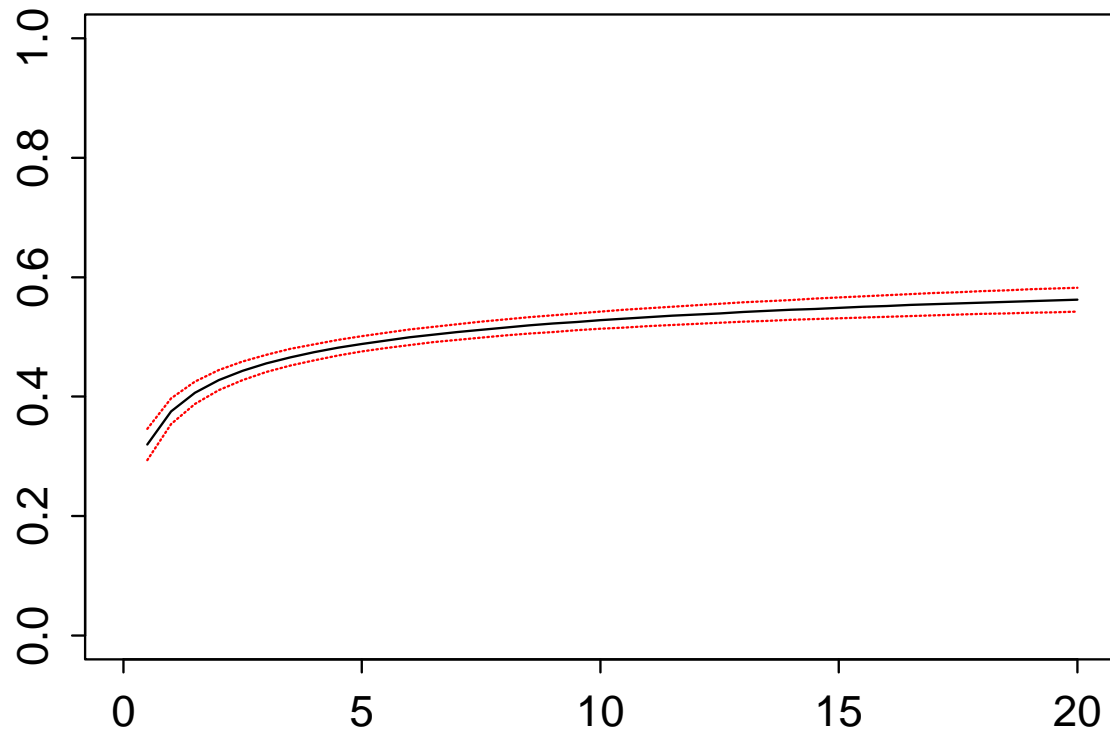
Let $\underline{x} = (x_{i1}, x_{i2}, \dots, x_{iM})$ be the vector of failure counts for the i th SMP. Then, the sampling distribution for the failure counts for the i th SMP in time interval j is

$$x_{ij} | \phi, \eta \stackrel{\text{indep}}{\sim} \text{Poisson} \left(\left(\frac{t_j}{\eta} \right)^\phi - \left(\frac{t_{(j-1)}}{\eta} \right)^\phi \right) \text{ for } j = 1, \dots, M,$$

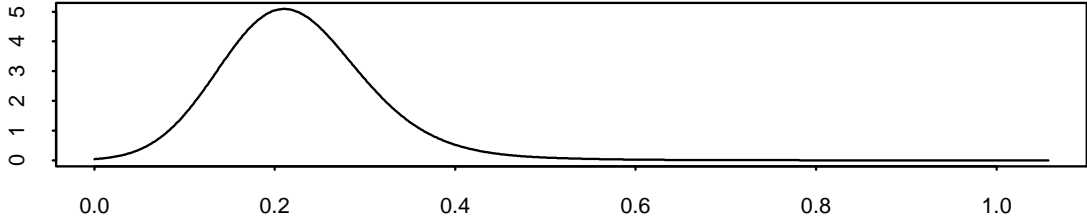
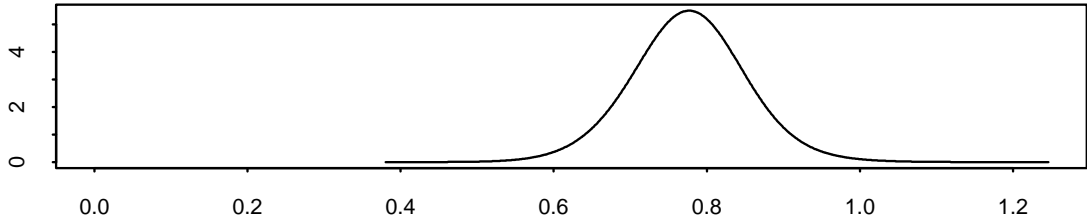
and \underline{x} has probability mass function

$$p(\underline{x} | \phi, \eta) = \prod_{j=1}^M \left[\frac{\left\{ \left(\frac{t_j}{\eta} \right)^\phi - \left(\frac{t_{(j-1)}}{\eta} \right)^\phi \right\}^{x_{ij}}}{x_{ij}!} \right] \exp \left\{ - \left(\frac{Mt}{\eta} \right)^\phi \right\}.$$

Posterior Distribution of θ



Predictive of New θ



Conclusions

- Science is subjective (what about the choice of a likelihood?)
- Bayes uses all available information
- Makes interpretation easier
- BAD NEWS: Computation is not generally available in standard statistical software packages.
- GOOD NEWS: They are possible (and practical) with advanced computational procedures